

First In-Class Exam Solutions
Math 246, Fall 2009, Professor David Levermore

- (1) [6] Suppose you have used the Runge-Kutta method to approximate the solution of an initial-value problem over the time interval $[0, 4]$ with 1000 uniform time steps. About how many uniform time steps would you need to reduce the global error of your approximation by a factor of 16?

Solution. The Runge-Kutta is fourth order, so its global error scales like h^4 . To reduce the error by a factor of 16, you must reduce h by a factor of $16^{\frac{1}{4}} = 2$. You must therefore double the number of time steps, which means you need 2000 uniform time steps.

- (2) [8] Sketch the graph that you expect would be produced by the following MATLAB commands.

```
[x, y] = meshgrid(-2:0.25:2, -2:0.25:2)
contour(x, y, y - x.^2, [-2, -2])
axis square
```

Solution. Your sketch should show both x and y axes marked from -2 to 2 and the parabola $y = x^2 - 2$. The tick marks on the axes should mark intervals of length $.25$.

- (3) [20] Find the explicit solution for each of the following initial-value problems and identify its interval of definition.

(a) $\frac{dy}{dt} = 5t^4 e^{-y}$, $y(0) = 10$.

Solution. This equation is separable. Its separated differential form is

$$e^y dy = 5t^4 dt, \quad \implies \quad e^y = t^5 + c.$$

The initial condition $y(0) = 10$ implies that $c = e^{10} - 0^5 = e^{10}$. Therefore $e^y = t^5 + e^{10}$, which can be solved as

$$y = \log(t^5 + e^{10}), \quad \text{with interval of definition } t > -e^2.$$

Here we need $t^5 > -e^{10}$ for the log to be defined. The interval of definition is obtained by taking the fifth root of both sides of this inequality.

(b) $\frac{dw}{dt} = \frac{t^2 - 2tw}{1 + t^2}$, $w(3) = 2$.

Solution. This equation is linear. Its linear normal form is

$$\frac{dw}{dt} + \frac{2t}{1 + t^2} w = \frac{t^2}{1 + t^2}.$$

An integrating factor is $\exp\left(\int_0^t \frac{2s}{1+s^2} ds\right) = \exp(\log(1 + t^2)) = 1 + t^2$, so that

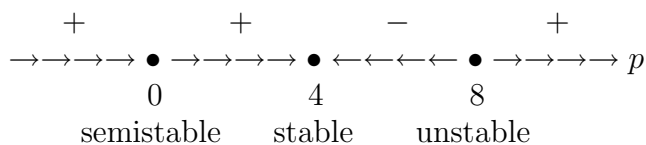
$$\frac{d}{dt}((1 + t^2)w) = (1 + t^2) \cdot \frac{t^2}{1 + t^2} = t^2, \quad \implies \quad (1 + t^2)w = \frac{1}{3}t^3 + c.$$

The initial condition $w(3) = 2$ implies that $c = (1 + 3^2) \cdot 2 - \frac{1}{3}3^3 = 20 - 9 = 11$. Therefore

$$w = \frac{\frac{1}{3}t^3 + 11}{1 + t^2}, \quad \text{with interval of definition } -\infty < t < \infty.$$

- (4) [16] Consider the differential equation $\frac{dp}{dt} = p^2(4-p)(8-p)$.
- Sketch its phase-line. Indicate all of the stationary (equilibrium) solutions and classify each as being either stable, unstable, or semistable.
 - If $p(0) = 10$, how does the solution $p(t)$ behave as $t \rightarrow \infty$?
 - If $p(0) = 6$, how does the solution $p(t)$ behave as $t \rightarrow \infty$?
 - If $p(0) = 2$, how does the solution $p(t)$ behave as $t \rightarrow \infty$?
 - If $p(0) = -2$, how does the solution $p(t)$ behave as $t \rightarrow \infty$?

Solution (a). The stationary solutions are $p = 0$, $p = 4$, and $p = 8$. A sign analysis of $p^2(4-p)(8-p)$ shows that the phase-line for this equation is therefore



Solution (b). The phase-line shows that if $p(0) = 10$ then $p(t) \rightarrow \infty$ as $t \rightarrow \infty$.

Solution (c). The phase-line shows that if $p(0) = 6$ then $p(t) \rightarrow 4$ as $t \rightarrow \infty$.

Solution (d). The phase-line shows that if $p(0) = 2$ then $p(t) \rightarrow 4$ as $t \rightarrow \infty$.

Solution (e). The phase-line shows that if $p(0) = -2$ then $p(t) \rightarrow 0$ as $t \rightarrow \infty$.

- (5) [16] Consider the following MATLAB function M-file.

```
function [t,y] = solveit(ti, yi, tf, n)

h = (tf - ti)/n;
t = zeros(n + 1, 1);
y = zeros(n + 1, 1);
t(1) = ti;
y(1) = yi;
for k = 1:n
    thalf = t(k) + h/2;
    yhalf = y(k) + (h/2)*(4*t(k) - (y(k))^2);
    t(k + 1) = t(k) + h;
    y(k + 1) = y(k) + h*(4*thalf - (yhalf)^2);
end
```

- What is the initial-value problem being approximated numerically?
- What is the numerical method being used?
- What are the output values of $t(2)$ and $y(2)$ that you would expect for input values of $t_i = 1$, $y_i = 2$, $t_f = 9$, $n = 40$?

Solution (a). The initial-value problem being approximated numerically is

$$\frac{dy}{dt} = 4t - y^2, \quad y(t_i) = y_i.$$

Solution (b). The Heun-midpoint method is being used. (This is clear from the lines defining $thalf$ and $yhalf$.)

Solution (c). When $t_i = 1$, $y_i = 2$, $t_f = 9$, $n = 40$ one has $h = (t_f - t_i)/n = (9 - 1)/40 = .2$, $t(1) = t_i = 1$, and $y(1) = y_i = 2$.

Setting $k = 1$ inside the “for” loop then yields

$$t_{\text{half}} = t(1) + h/2 = 1 + .1 = 1.1$$

$$y_{\text{half}} = y(1) + (h/2) (4 t(1) - y(1)^2) = 2 + .1 (4 \cdot 1 - 2^2) = 2,$$

$$t(2) = t(1) + h = 1 + .2 = 1.2,$$

$$y(2) = y(1) + h (4 t_{\text{half}} - y_{\text{half}}^2) = 2 + .2 (4 \cdot 1.1 - 2^2).$$

The above answer got full credit, but $y(2) = 2.08$ if you worked out the arithmetic.

- (6) [14] What is the maximum amount a student can borrow with a five-year loan at an interest rate of 5% per year compounded continuously assuming that she can make payments continuously at a constant rate of 2400 dollars per year? Hint: Write down an initial-value problem that governs $B(t)$, the balance of the loan at t years.

Solution. Because the loan get paid-off in five years, the balance $B(t)$ satisfies the initial-value problem

$$\frac{dB}{dt} = .05B - 2400, \quad B(5) = 0.$$

The equation is linear and can be put into the integrating factor form

$$\frac{d}{dt}(e^{-.05t}B) = -2400e^{-.05t},$$

which implies that

$$e^{-.05t}B = 48000e^{-.05t} + c.$$

The initial condition $B(5) = 0$ implies that $c = -48000e^{-.25}$. Therefore

$$B(t) = 48000 - 48000e^{.05(t-5)}.$$

The maximum amount she can borrow is $B(0) = 48000(1 - e^{-.25})$.

- (7) [20] Give an implicit general solution to each of the following differential equations.
 (a) $(3x^2 \sin(y) + e^x) dx + (x^3 \cos(y) + 2y) dy = 0$.

Solution: This differential form is *exact* because

$$\partial_y(3x^2 \sin(y) + e^x) = 3x^2 \cos(y) = \partial_x(x^3 \cos(y) + 2y) = 3x^2 \cos(y).$$

We can therefore find $H(x, y)$ such that

$$\partial_x H(x, y) = 3x^2 \sin(y) + e^x, \quad \partial_y H(x, y) = x^3 \cos(y) + 2y.$$

Integrating the first equation with respect to x yields

$$H(x, y) = x^3 \sin(y) + e^x + h(y).$$

Plugging this expression for $H(x, y)$ into the second equation gives

$$x^3 \cos(y) + h'(y) = \partial_y H(x, y) = x^3 \cos(y) + 2y,$$

which yields $h'(y) = 2y$. Taking $h(y) = y^2$, a general solution is therefore given implicitly by

$$x^3 \sin(y) + e^x + y^2 = c.$$

(b) $(3x^2y + 2xy + y^3) dx + (x^2 + y^2) dy = 0$.

Solution. This differential form is *not exact* because

$$\partial_y(3x^2y + 2xy + y^3) = 3x^2 + 2x + 3y^2 \neq \partial_x(x^2 + y^2) = 2x.$$

You therefore seek an *integrating factor* μ such that

$$\partial_y[(3x^2y + 2xy + y^3)\mu] = \partial_x[(x^2 + y^2)\mu].$$

Expanding the partial derivatives yields

$$(3x^2y + 2xy + y^3)\partial_y\mu + (3x^2 + 2x + 3y^2)\mu = (x^2 + y^2)\partial_x\mu + 2x\mu.$$

If you set $\partial_y\mu = 0$ then this becomes

$$(3x^2 + 2x + 3y^2)\mu = (x^2 + y^2)\partial_x\mu + 2x\mu,$$

which reduces to $\partial_y\mu = 3\mu$. This yields the integrating factor $\mu = e^{3x}$.

Because e^{3x} is an integrating factor, the differential form

$$e^{3x}(3x^2y + 2xy + y^3) dx + e^{3x}(x^2 + y^2) dy = 0 \quad \text{is exact.}$$

You can therefore find $H(x, y)$ such that

$$\partial_x H(x, y) = e^{3x}(3x^2y + 2xy + y^3), \quad \partial_y H(x, y) = e^{3x}(x^2 + y^2).$$

Integrating the second equation with respect to y yields

$$H(x, y) = e^{3x}(x^2y + \frac{1}{3}y^3) + h(x).$$

Plugging this expression for $H(x, y)$ into the first equation gives

$$3e^{3x}(x^2y + \frac{1}{3}y^3) + e^{3x}2xy + h'(x) = \partial_x H(x, y) = e^{3x}(3x^2y + 2xy + y^3),$$

which yields $h'(x) = 0$. Taking $h(x) = 0$, a general solution is therefore given implicitly by

$$e^{3x}(x^2y + \frac{1}{3}y^3) = c.$$