

Optimal control for sampling the transition path process and estimating rates

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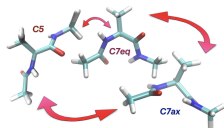
Joint work with:

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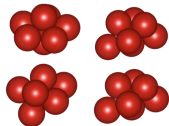
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Motivation

We would like to study rare transitions in systems governed by SDEs



Conformational changes in biomolecules



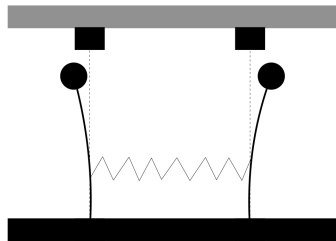
Cluster rearrangements

Langevin SDE

$$\begin{cases} dX_t = m^{-1}P_t dt \\ dP_t = -(\nabla U + \gamma P_t)dt + \sqrt{2\gamma\beta^{-1}}m dW_t^n \end{cases}$$

Overdamped Langevin SDE

$$dX_t = -\nabla U(X_t)dt + \sqrt{2\beta^{-1}}dW_t^n$$

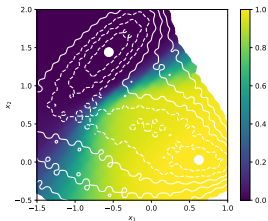
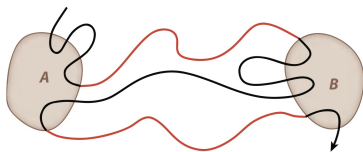


Oscillators with multiple equilibria or stable modes

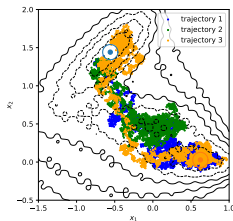
Transition path theory

Forward and backward committor function

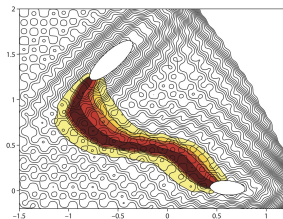
$$\begin{cases} q^+(y) = \mathbb{P}\{\tau_B^+(y) < \tau_A^+(y)\} \\ q^-(y) = \mathbb{P}\{\tau_A^-(y) < \tau_B^-(y)\} \end{cases}$$



Committor function



Reactive trajectories



Probability current (E and Vanden-Eijnden, 2010)

Reactive current: $J_R(x) = \beta^{-1} Z^{-1} e^{-\beta U(x)} \nabla q(x)$

Transition rate: $\nu_R = \beta^{-1} Z^{-1} \int_{\Omega_{AB}} \|\nabla q(x)\|^2 e^{-\beta U(x)} dx$

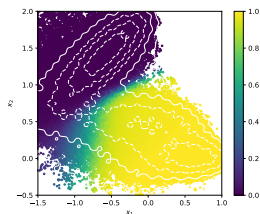
Committor function

The **forward committor function** satisfies

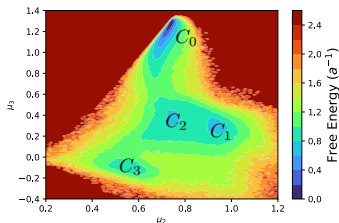
$$\begin{cases} Lq(x) = \nabla U \cdot \nabla q - \beta^{-1} \Delta q = 0, & x \in \Omega \setminus (A \cup B) \\ q(x) = 0, & x \in \partial A \\ q(x) = 1, & x \in \partial B \end{cases}$$

The **backward committor function**

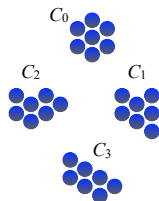
$$\begin{cases} \text{Langevin Equation:} & q^-(x, p) = 1 - q(x, -p) \\ \text{Overdamped Langevin Equation:} & q^-(x) = 1 - q(x) \end{cases}$$



NN approximation



Reduced model for LJ7



Stochastic optimal control

Inexact committor \rightarrow inexact transition rate.

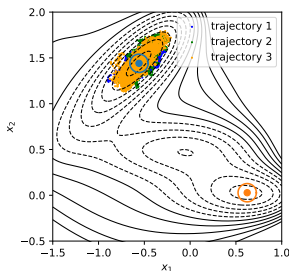
Our remedy: stochastic optimal control.

SDEs with rare transitions

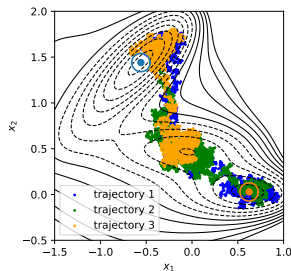
$$dX_t = -b(X_t)dt + \sigma(X_t)dW_t^n$$

SDEs with stochastic controller

$$d\tilde{X}_t = \left[-b(\tilde{X}_t) + \sigma\sigma^\top(\tilde{X}_t)v(t, \tilde{X}_t) \right] dt + \sigma(\tilde{X}_t)dW_t$$



(a) trajectories without control



(b) $\sigma\sigma^\top v = 2\beta^{-1}\nabla \log q^+$

Related work and our goal

- Lu and Nolen (2015): Doob's h-transform; transition path process for Ito's SDEs.
- Gao, Li, Li, Liu (2022): optimal control problem for sampling reactive trajectories for overdamped Langevin dynamics and a rigorous proof for the optimal controller $\frac{\beta}{2} \nabla \log q$
- Zhang, Sahai, Marzouk (2022): fixed time horizon, even a rough approximation to the backward Kolmogorov equation yields a good controller
- Zhang, Hartmann, Schuette (2016): transition rate is overestimated due to inexact committors from the reduced model

We propose:

To combine **transition path theory** with **stochastic optimal control** for a more accurate estimate of **transition rates** and **sampling transition paths**.

Theorem

(Yuan, Shah, Bentz, and Cameron, 2023)

$$d\tilde{X}_t = \left[-b(\tilde{X}_t) + \sigma\sigma^\top(\tilde{X}_t)v(t, \tilde{X}_t) \right] dt + \sigma(\tilde{X}_t)dW_t$$

Assume that $\sigma(X_t) \in \mathbb{R}^{d \times r}$: full rank. Cost functional:

$$C_x[v(\cdot)] = \mathbb{E}_P \left[\frac{1}{2} \int_0^{\tau_{AB}} \|\sigma^\top(Y_s)v(Y_s)\|^2 ds + g(Y_\tau) \mid X_0 = x \right],$$

$$\text{where } g(x) = \begin{cases} +\infty, & x \in \bar{A} \\ 0, & x \in \bar{B} \end{cases}, \quad \tau_{AB} = \inf\{t > 0 \mid X_t \in \bar{A} \cup \bar{B}\}$$

Under non-restrictive assumptions,

$$\mathbf{c}^*(\mathbf{x}) := \inf_{\mathbf{v} \in \mathcal{V}} \mathbf{C}_x[\mathbf{v}(\cdot)] = -\log \mathbf{q}^+(\mathbf{x}). \quad (1)$$

The corresponding optimal control \mathbf{v}^* satisfies

$$\sigma^\top \mathbf{v}^* = \sigma^\top \nabla \log \mathbf{q}^+. \quad (2)$$

Cases of interest

Overdamped Langevin equations in collective variables

$$dX_t = [-M(X_t)\nabla F(X_t) + \beta^{-1}\nabla \cdot M(X_t)]dt + \sqrt{2\beta^{-1}}M(X_t)^{\frac{1}{2}}dW_t.$$

$$\Rightarrow dX_t = [-M(X_t)\{\nabla F(X_t) - 2\beta^{-1}\nabla \log q^+\} + \beta^{-1}\nabla \cdot M(X_t)]dt + \sqrt{2\beta^{-1}}M(X_t)^{\frac{1}{2}}dW_t.$$

Langevin equations

$$\begin{cases} dx_t = m^{-1}p dt \\ dp_t = (-\nabla U(x_t) - \gamma_f p) dt + \sqrt{2\gamma_f\beta^{-1}}mdw_t \end{cases}$$

$$\Rightarrow \begin{cases} dx_t = m^{-1}p dt \\ dp_t = (-\nabla U(x_t) - \gamma_f p + 2\gamma_f\beta^{-1}m\nabla_p \ln q) dt + \sqrt{2\gamma_f\beta^{-1}}mdw_t \end{cases}$$

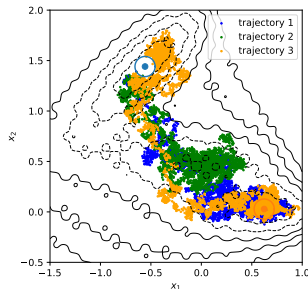
Challenges

- 1 Computation of the committor function in high-dimensional space

$$\begin{cases} Lq(x) = \nabla U \cdot \nabla q - \beta^{-1} \Delta q = 0, & x \in \Omega_{AB} \\ q(x) = 0, & x \in \partial A \\ q(x) = 1, & x \in \partial B \end{cases}$$

- 2 Rate estimation from crossover times

$$\nu_{AB} = \lim_{T \rightarrow \infty} \frac{N_{AB}}{T}$$



Solution to the committor

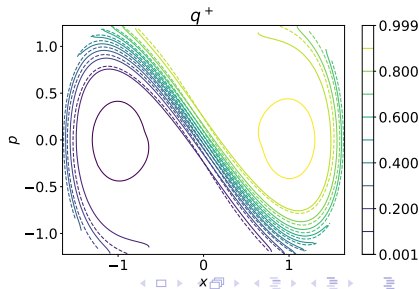
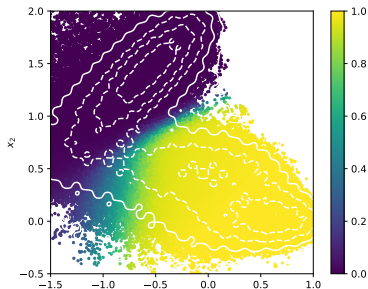
- **Overdamped Langevin equation:** scheme by Li, Lin, Ren (2019)

$$q(x; \theta) = (1 - \chi_A(x))[(1 - \chi_B(x))\mathcal{N}(x; \theta) + \chi_B(x)], \quad x \in \Omega_{AB},$$

$$\text{Loss}(\theta) = \frac{1}{K} \sum_{k=1}^K \left[\nabla q(x_k; \theta)^\top M(x_k) \nabla q(x_k; \theta) \frac{e^{-\beta F(x_k)}}{\rho(x_k)} \right].$$

- **Langevin equation:** PINN by Karniadakis et al. (2022)

$$\begin{aligned} \text{Loss}(\theta) = \frac{1}{K} \sum_{(x_k, p_k) \in \Omega_{AB}} |\mathcal{L}\mathcal{N}(x_k, p_k; \theta)|^2 &+ \frac{1}{K_{\partial A}} \sum_{(x_k, p_k) \in \partial A} |\mathcal{N}(x_k, p_k)|^2 \\ &+ \frac{1}{K_{\partial B}} \sum_{(x_k, p_k) \in \partial B} |\mathcal{N}(x_k, p_k) - 1|^2 \end{aligned}$$



Estimation of transition rate

Transition rate

$$\nu_{AB} = \lim_{T \rightarrow \infty} \frac{N_{AB}}{T}$$

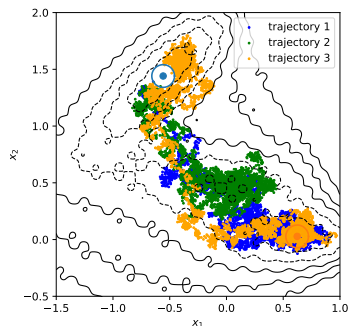
- inaccurate estimate of the committor function
- suboptimal choice set of collective variables when model reduction is used

$$\nu_{AB} = \frac{\rho_{AB}}{\mathbb{E}[\tau_{AB}]}$$

where

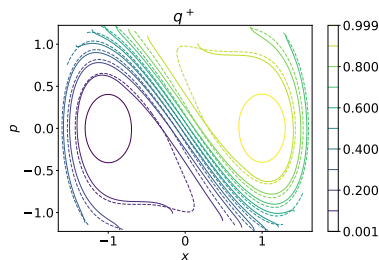
$$\rho_{AB} = \int_{\Omega_{AB}} \mu q^+ q^- dx$$

$$\nu_{AB} = \beta^{-1} Z^{-1} \int_{\Omega_{AB}} \|\nabla q(x)\|^2 e^{-\beta U(x)} dx$$

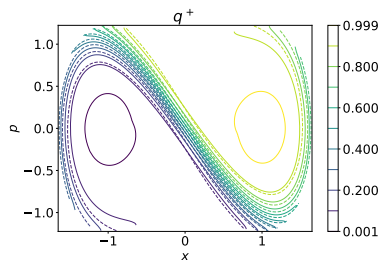


Duffing Oscillator in 1D

$$d \begin{bmatrix} X_t \\ P_t \end{bmatrix} = \begin{bmatrix} -X_t(X_t^2 - 1) - \frac{1}{2}P_t \\ 0 \end{bmatrix} dt + \sqrt{\epsilon} \begin{bmatrix} 0 \\ dW_t \end{bmatrix}.$$



(a) $\epsilon = 0.1$



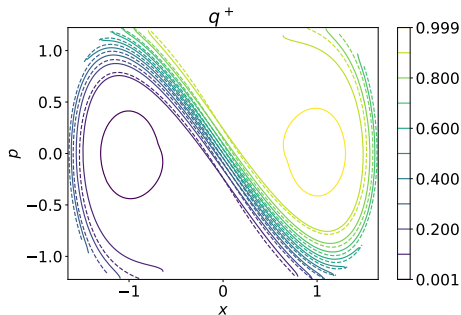
(b) $\epsilon = 0.05$

Duffing oscillator $\epsilon = 0.1$				
	Simul., o/c	Simul., w/o o/c	TPT, NN	TPT, FEM
ν_{AB}	[5.50e-3, 6.07e-3]	[5.76e-3, 6.01e-3]	4.53e-3	5.74e-3
Duffing oscillator $\epsilon = 0.05$				
ν_{AB}	[5.53e-4, 6.06e-4]	[5.49e-4, 6.51e-4]	4.72e-4	5.49e-4

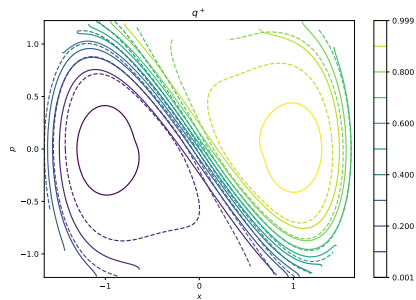
Effect of undertrained NN

	wMAE	wRMSE	$\mathbb{E}[\tau_{AB}]$
Case 0 (epoch 500)	1.3e-2	2.0e-2	7.34 \pm 0.33
Case 1 (epoch 300)	4.9e-2	6.1e-2	7.88 \pm 0.36
Case 2 (epoch 150)	6.0e-2	7.7e-2	8.48 \pm 0.84
Case 3 (epoch 125)	7.9e-2	10.2e-2	12.18 \pm 2.49
Case 4 (epoch 100)	13.6e-2	16.7e-2	48.86 \pm 5.71

Ground truth $\mathbb{E}[\tau_{AB}] = \mathbf{7.48 \pm 0.49}$



case 0

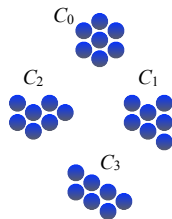
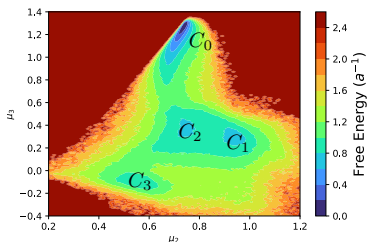


case 1

Lennard-Jones-7 in 2D

$$V_{\text{pair}}(r) = 4a \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

$$V_{\text{LJ}}(x) = \sum_{\substack{i,j=1 \\ i < j}}^7 V_{\text{pair}}(\|x_i - x_j\|)$$



Reduced model

$$c_i(x) = \sum_{i \neq j} \frac{1 - \left(\frac{r_{ij}}{1.5\sigma} \right)^8}{1 - \left(\frac{r_{ij}}{1.5\sigma} \right)^{16}}, \quad r_{ij} = \|x_i - x_j\|.$$

$$\mu_k(x) = \frac{1}{7} \sum_{i=1}^7 (c_i(x) - \bar{c}(x))^k, \quad \text{where } \bar{c}(x) = \frac{1}{7} \sum_{j=1}^7 c_j(x).$$

	Simul., o/c	Simul., w/o o/c	TPT, NN	TPT, FEM
Dimension	14D	14D	2D	2D
ν_{AB}	0.022, [0.020, 0.024]	0.025, [0.019, 0.033]	0.097	0.086

Future work

Overestimation of transition rates in reduced model
(Zhang, Hartmann, and Schuette, 2016)

$$\nu_{AB} \leq \tilde{\nu}_{AB} = \nu_{AB} + \frac{1}{\beta} \int_{\Omega_{AB}} \nabla[q(x) - \tilde{q}(\xi(x))]^\top M(x) \nabla[q(x) - \tilde{q}(\xi(x))] \mu(x) dx$$

Develop a methodology for learning collective variables that represent the dynamics well.

Reference

Jiaxin Yuan, Amar Shah, Channing Bentz, and Maria Cameron. *Optimal control for sampling the transition path process and estimating rates*. Communications in Nonlinear Science and Numerical Simulation. Volume 129, February 2024, 107701. [ArXiv: 2305.17112](#).