

1. Read section 2.5 of *Lay* at least through the material in the box on p.146. Then do problem 31 on p.150. In part (a) use the command  $[L,U]=lu(A)$ . In part (b) use the backslash operator twice. (See equation (2) on p.143.)

MATLAB uses finite precision arithmetic, so there will be round-off error in most calculations. In order to minimize the effect of round-off error the Gaussian elimination process must be modified by introducing the concept of *partial pivoting*. (The definition is given on p.20 of *Lay*.) The MATLAB command  $A \setminus \mathbf{b}$  implements Gaussian elimination with partial pivoting. What accuracy should one expect ?

MATLAB carries about 15 digits so its basic calculations are very accurate, with errors about  $10^{-15}$ . We can quantify this more precisely. The numbers that can be represented in MATLAB are called floating point numbers. There is a special number in MATLAB denoted by *eps*, that is defined to be the distance from 1 to the next floating point number. The command `eps` will produce *eps* for the computer you are using; *eps* is approximately  $2.22e - 16$ . The significance of *eps* is that it determines the round-off error committed when a number is rounded: If a positive number  $a$  is rounded, the round-off error is approximately  $a \times eps$ .

Consider the linear system

$$A\mathbf{x} = \mathbf{b},$$

and let  $\mathbf{x}^*$  be the computed solution (the number produced by the computer). There are two measures of accuracy of the computed solution  $\mathbf{x}^*$ . The *error* in  $\mathbf{x}^*$  is defined to be

$$\mathbf{e} = \mathbf{x} - \mathbf{x}^*,$$

and the *residual* is defined to be

$$\mathbf{r} = \mathbf{b} - A\mathbf{x}^*.$$

The *norm* (size) of  $\mathbf{e}$  is one measure of the accuracy of  $\mathbf{x}^*$ ; if the norm of  $\mathbf{e}$  is small, then  $\mathbf{x}^*$  is close to  $\mathbf{x}$ . The second measure of accuracy of  $\mathbf{x}^*$  is the norm of  $\mathbf{r}$ ; if the norm of  $\mathbf{r}$  is small, then  $\mathbf{x}^*$  nearly satisfies the linear system.

There are two principles that indicate the accuracy of the solution  $\mathbf{x}^*$  produced by Gaussian elimination with partial pivoting ( the method used in  $A \setminus \mathbf{b}$ ). The first is that the norm of the residual is nearly always small; to be more precise,

$$\text{Norm of } \mathbf{r} \propto \text{Norm of } \mathbf{x} \times \text{Norm of } A \times eps,$$

*i.e.*, for a moderate sized problem the norm of the residual is approximately *eps*. The second principle is that

$$\text{Norm of } \mathbf{e} \propto \text{Norm of } \mathbf{x} \times \text{cond}(A) \times eps,$$

where  $\text{Cond}(A)$  is a number that measures how close  $A$  is to being singular. The norm of a vector or a matrix is a measure of the size of the vector or the matrix, respectively. If  $A$

is nearly singular, then  $\text{Cond}(A)$  is large, and the error may be large. Matrices for which  $\text{cond}(A)$  is large are called *ill-conditioned*. If  $\text{Cond}(A) \approx 10^t$ , then the error would be about  $10^t \times \text{eps} \approx 10^{16-t}$ , i.e., we would have lost approximately  $t$  digits of accuracy.  $\text{Cond}(A)$  can be found with the command **cond(A)**. When  $A \setminus \mathbf{b}$  is used, if the calculations indicate that  $A$  is ill-conditioned, a warning message is printed, and a number RCOND which is an approximation to  $1/\text{cond}(A)$ , is printed. The following two problems illustrate these principles. Note: type **format long** before you do the requested calculations.

2. The  $n \times n$  matrix  $H_n$  whose elements are given by  $h_{i,j} = 1/(i + j - 1)$  is very ill-conditioned if  $n$  is large; it is called the *Hilbert Matrix*. It can be generated in MATLAB with the command **hilb(n)**. Let  $A$  be the Hilbert matrix of size 11. Let  $\mathbf{x} = \mathbf{ones}(11,1)$ , and let  $\mathbf{b} = A\mathbf{x}$ . Now solve the system  $A\mathbf{x} = \mathbf{b}$ , obtaining  $\mathbf{x}^*$ . Since we know  $\mathbf{x}$  exactly we can compute  $\mathbf{e}$ . Do this and also compute  $\mathbf{r}$ . What are the norms of these vectors? Are the above principles satisfied for this example?

3. Let

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 4 & 5 & 6 & 3 & -2 \\ 7 & 8 & 9 & -3 & 3 \\ 3 & 4 & -2 & -4 & 10 \\ 1 & 2 & 3 & 4 & 6 \end{pmatrix}.$$

Find  $\text{cond}(A)$ .  $A$  is not ill-conditioned. Solve  $A\mathbf{x} = \mathbf{b}$ , where  $\mathbf{b} = (55, 34, 53, 39, 60)^T$ . How small would you expect  $\mathbf{e}$  and  $\mathbf{r}$  to be? The exact solution is  $\mathbf{x} = (1, 2, 3, 4, 5)^T$ . Calculate  $\mathbf{e}$  and  $\mathbf{r}$ . Are the above principles satisfied for this example?