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# Solving the steady state diffusion equation with uncertainty Final Presentation

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May 6, 2012

Introduction	Karhunen-Loéve expansion	Monte-Carlo method	Stochastic Galerkin method	Results
Problem				

The equation to be solved is

$$-\nabla \cdot (k(x,\omega)\nabla u(x,\omega)) = f(x) , \qquad (1)$$

where  $k = e^{a(x,\omega)}$  is a lognormal random field.

- Assume a bounded spatial domain  $D \subset \mathbb{R}^2$ .
- The boundary conditions are deterministic.

$$u(x,\omega) = g(x) \text{ on } \partial D_D$$
  
 $rac{\partial u}{\partial n} = 0 \text{ on } \partial D_n .$ 

• Models groundwater flow through a porous medium [15].

Introduction	Karhunen-Loéve expansion	Monte-Carlo method	Stochastic Galerkin method	Results
Outline				

- Approximate the random field using the Karhunen-Loéve expansion.
- **2** Solve the PDE using stochastic Galerkin method.
- Compare mean and variance of the solution to those obtained using the Monte-Carlo method.

# Karhunen-Loéve expansion

The expansion is

$$a(x,\vec{\xi}) = a_0(x) + \sum_{s=1}^{\infty} \sqrt{\lambda_s} a_s(x) \xi_s . \qquad (2)$$

- $a_0(x)$  is the mean of the random field.
- The random variables ξ<sub>s</sub> are uncorrelated with E[ξ<sub>s</sub>] = 0, Var[ξ<sub>s</sub>] = 1.
- The  $\lambda_s$  and  $a_s(x)$  are eigenpairs which satisfy

$$(Ca_s)(x_1) = \int_D C(x_1, x_2)a_s(x_2)dx_2 = \lambda_s a_s(x_1)$$
, (3)

where  $C(x_1, x_2)$  is the covariance function of the random field.

# Discretization of the eigenvalue problem

- The square domain *D* is discretized intervals of equal size *h* in each direction.
- The eigenvalues of the covariance operator satisfy

$$h^2 C V = \Lambda V . \tag{4}$$

where  $C_{ij} = C(x_i, x_j)$ .

• The approximation of the eigenfunctions are

$$a_s(x_i) = \frac{1}{h} V_{is} \tag{5}$$

### Discretization of the eigenvalue problem

• Alternatively, *q* samples of the random field can be used to form the sample covariance matrix:

$$\widehat{C}_{ij} = \frac{1}{q} \sum_{k=1}^{q} (a(x_i, \omega_k) - \hat{a}_i)(a(x_j, \omega_k) - \hat{a}_j)$$
(6)

where  $\hat{a}_i$  is the sample mean.

• The covariance function for the Gaussian random field with mean  $\mu$  and variance  $\sigma^2$  is

$$C_g((x_1, y_1), (x_2, y_2)) = \sigma^2 \exp\left(\frac{-|x_1 - x_2|}{b_x} + \frac{-|y_1 - y_2|}{b_y}\right)$$
(7)

where  $b_x$ ,  $b_y$  are the correlation lengths.

• The eigenvalues and eigenfunctions have analytic expressions for this covariance function.

# Validation of eigenpairs

• Two methods for finding eigenpairs verified by comparing with analytic expressions for the Gaussian random field.

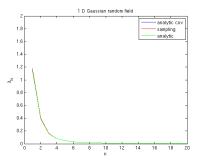


Figure: Eigenvalues of Gaussian random field with parameters b = 1, q = 10000 computed using analytic expression and the two covariance matrices.

 The covariance function for the lognormal random field can be written as a function of the Gaussian covariance function.

$$C_{l}((x_{1}, y_{1}), (x_{2}, y_{2})) = e^{2\mu + \sigma^{2}} (e^{C_{g}((x_{1}, y_{1}), (x_{2}, y_{2}))} - 1)$$
[9]. (8)

- This expression is used to build the covariance matrix and find the eigenpairs.
- The sampling method would allow this model to be used when structure of the random field is unknown but can be sampled at various points in space.

# Karhunen-Loéve expansion

The lognormal random field can be approximated two ways:

$$k(x,\xi) = \exp[a_0(x) + \sum_{i=1}^{m_g} \sqrt{\lambda_i} a_i(x)\xi_i]$$
(9)

$$\hat{k}(x,\eta) = k_0(x) + \sum_{i=1}^{m_i} \sqrt{\mu_i} k_i(x) \eta_i .$$
 (10)

- {ξ<sub>i</sub>} are independent Gaussian random variables, so the joint probability density function, ρ(ξ), is known.
- The joint density function of the random variables,  $\eta_i$ , is needed.
- Let  $m = \max(m_g, m_l)$  and the joint density function,  $\hat{\rho}(\eta)$ , is found using a change of variables.

- Define matrices  $A = [a_1|a_2|...|a_m]$  and  $K = [k_1|k_2|...|k_m]$ where the columns are the eigenfunctions evaluated at the points in the spatial discretization.
- Define the mass matrix  $B_{ij} = \int_D \phi_i(x)\phi_j(x)dx$ .
- A was normalized so that  $A^T B A = I$ .
- Define the diagonal matrices  $\Lambda = \text{diag}(\lambda_1, \lambda_2, ..., \lambda_m)$  and  $M = \text{diag}(\mu_1, \mu_2, ..., \mu_m)$ .
- Define vectors  $\xi = [\xi_1, \xi_2, ..., \xi_m]^T$  to be the standard normal random variables in the Gaussian random field and  $\eta = [\eta_1, \eta_2, ..., \eta_m]^T$  to be the unknown random variables in the lognormal expansion.

$$\Lambda A^T B(k(x,\xi) - a_0(x)) = \Lambda A^T B(\widehat{k}(x,\eta) - a_0(x)) .$$
(11)

$$\xi = g(\eta) = \Lambda A^{T} B(\ln(k_0 + KM\eta) - a_0) .$$
 (12)

- $\hat{\rho}(\eta) = \rho(g(\eta))|J(\eta)|$  describes the density for  $\eta$  such that  $k_0 + KM\eta > 0$ .
- |J(η)| is the absolute value of the determinant of the Jacobian, which we can find since g(η) is differentiable.

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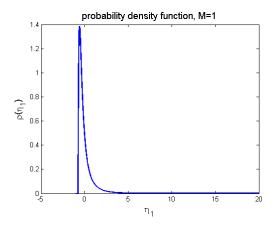


Figure: Probability density function for 1d field m = 1, b = 10.

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### Probability density function

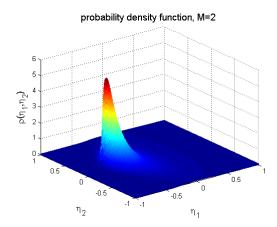


Figure: Probability density function for m = 2, b = 10.

- The joint density function can be used to find the marginal density functions which have mean 0 and variance 1 as expected.
- Samples of k(x, ξ) were generated with m N(0, 1) samples for each instance.
- To find samples of  $\hat{k}(x,\eta)$ , accept/reject sampling is used.
- Uniform samples over the support of density function are generated and the probability density function evaluated at those values.
- In addition another uniform sample on (0,1) is generated, if this value is above the value of the pdf it is kept as a sample of the distribution.
- The sample mean of  $k(x,\xi)$  and  $\hat{k}(x,\eta)$  can now be compared.

#### Probability density function

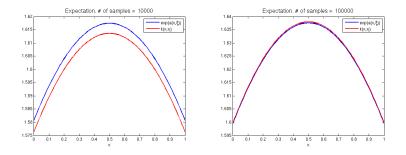


Figure: Compare  $E[\hat{k}(x,\eta)]$  and  $E[k(x,\xi)]$  using Monte-Carlo method. Lognormal samples found using accept/reject technique.

## Deterministic diffusion equation

• For the Monte-Carlo method the deterministic diffusion equation needs to be solved.

$$-\nabla \cdot (k(x)\nabla u(x)) = f(x) . \tag{13}$$

- Let *D* be square and discretize with bilinear elements on quadrilaterals of size *h* by *h*.
- Let  $\phi_j(x)$  denote the basis functions.

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# Deterministic diffusion equation

Find 
$$u(x) \in H^1_E(D) = \{u \in H^1(D) : u = g(x) \text{ on } \partial D_d\}$$
 such that  

$$\int_D k(x) \nabla u(x) \cdot \nabla v(x) dx = \int_D f(x) v(x) dx$$
(14)

is satisfied for all  $v(x) \in H_0^1(D)$ .

### Deterministic diffusion equation

• The finite element solution is

$$u_h(x) = \sum_{j=1}^n u_j \phi_j(x) + \sum_{j=n+1}^{n+n_d} u_j \phi_j(x) .$$
 (15)

where n is the number of elements on the interior and  $n_d$  is the number of elements on the boundary.

• To find the coefficients  $u_j$ , solve Au = b where

$$A_{ij} = \int_D k(x) \nabla \phi_j(x) \cdot \nabla \phi_i(x) \, dx \tag{16}$$

$$b_{i} = \int_{D} \phi_{i}(x) f(x) \, dx - \sum_{j=n+1}^{n+n_{d}} u_{j} \int_{D} k(x) \nabla \phi_{j}(x) \cdot \nabla \phi_{i}(x) \, dx$$
(17)

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### Deterministic diffusion equation

- Implemented with Matlab package Incompressible Flow & Iterative Solver Software(IFISS) [10].
- $D = [0,1] \times [0,1].$

• 
$$f(x) = 1$$
,  $g(x) = 0$ ,  $k(x) = 1$ ,  $h = 0.0625$ ,  $n_d = 64$ ,  $n = 225$ 

• Analytic solution [1]:

$$u(x,y) = \frac{16}{\pi^4} \sum_{l=0}^{\infty} \sum_{k=0}^{\infty} \frac{\sin((2k+1)\pi x)\sin((2l+1)\pi y)}{(2k+1)(2l+1)((2k+1)^2 + (2l+1)^2)}$$
(18)

$$\frac{||u_h(x) - u(x)||_2}{||u(x)||_2} = 3.31 \times 10^{-3}$$
(19)

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#### Deterministic diffusion equation

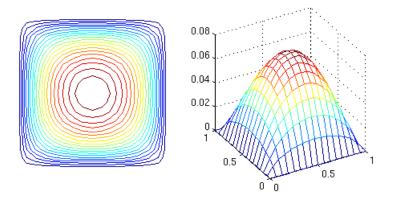


Figure: Deterministic solution, k(x) = 1

- Use the deterministic solver for each of q finite element problems, denoting the solution  $u_h^i(x)$  for i = 1, ..., q.
- The sample mean of the solution is

$$E_{q}[u_{h}] = \frac{1}{q} \sum_{i=1}^{q} u_{h}^{i}(x) .$$
 (20)

$$\operatorname{Var}_{q}[u_{h}] = \frac{1}{q-1} \sum_{i=1}^{q} (u_{h}^{i}(x)^{2} - E_{q}[u_{h}]^{2})$$
(21)

The error in the mean is  $E[u] - E_a[u_h] = E[u] - E[u_h] + E[u_h] - E_a[u_h].$  • Using the KL expansion from the Gaussian random field

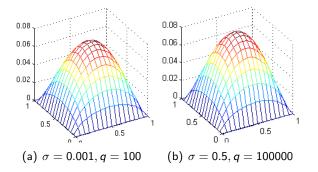
$$k(x,\vec{\xi}) = \exp[a_0(x) + \sum_{s=1}^{m_g} \sqrt{\lambda_s} a_s(x)\xi_s]$$
(22)

where  $\xi_s$  are independent and N(0,1) [13].

- Sample the  $m_g$  standard normal random variables q times to produce samples  $k_i(x)$  for i = 1, ..., q.
- Running method with  $\sigma = 0$  differs from the deterministic solution  $\sim 10^{-15}$ .

#### Monte Carlo Method

Figure: Monte Carlo solution:  $E[k(x,\xi)] = 1$ , f(x) = 1, m = 5, g(x) = 0.



# Stochastic weak formulation

- Write the solution as combination of basis functions which can be used to estimate statistical properties of the solution.
- The stochastic basis functions are analagous to the spatial basis functions used in the deterministic method.
- Using the KL expansion, the probability space,  $\Omega$ , is approximated by  $\Gamma$ , where  $\Gamma$  is the support of the joint density function of the random variables in the expansion.
- The weak formulation of the problem is to find  $u \in H^1(D) \otimes L^2(\Gamma)$  such that the following holds for all  $v \in H^1_0(D) \otimes L^2(\Gamma)$

$$\int_{\Gamma} \int_{D} \widehat{k}(x,\eta) \nabla u \cdot \nabla v \widehat{\rho}(\eta) \, dx \, d\eta = \int_{\Gamma} \int_{D} f v \widehat{\rho}(\eta) \, dx \, d\eta \quad (23)$$

- The spatial discretization uses the same bilinear elements as the deterministic problem  $(\phi_i(x))$ .
- The stochastic discretization uses chaos polynomials

$$\psi_{\mathbf{j}}(\eta) = \psi_{j_1}(\eta_1)\psi_{j_2}(\eta_2)...\psi_{j_m}(\eta_m) .$$
 (24)

• The chaos polynomials are chosen to be orthonormal so that  $E[\psi_{\mathbf{i}}(\eta)\psi_{\mathbf{j}}(\eta)] = \delta_{\mathbf{ij}}.$ 

• The number of basis polynomials is chosen by setting an upper bound (*N*) on the degree of the polynomials.

$$\deg(\psi_{\mathbf{j}}) = \deg(\psi_{j_1}) + \ldots + \deg(\psi_{j_m}) \le N \quad \forall \mathbf{j} \qquad (25)$$

• The polynomials can be reindexed  $j=1,...,n_\eta$  where

$$n_{\eta} = \binom{N+m}{m} . \tag{26}$$

### Stochastic Galerkin method

• The solution is written as a combination of products of the two basis functions.

$$u_{h}(x,\eta) = \sum_{i=1}^{n_{x}} \sum_{j=1}^{n_{\eta}} u_{ij}\phi_{i}(x)\psi_{j}(\eta)$$
(27)

$$v(x,\eta) = \phi(x)\psi(\eta) \tag{28}$$

• The problem is to find the coefficients  $u_{ij}$  which satisfy

$$\sum_{i=1}^{n_{x}} \sum_{j=1}^{n_{\eta}} \int_{\Gamma} \int_{D} u_{ij} \widehat{k}(x,\eta) \nabla \phi_{i}(x) \cdot \nabla \phi_{k}(x) \psi_{j}(\eta) \psi_{l}(\eta) \widehat{\rho}(\eta) dx d\eta$$
$$= \int_{\Gamma} \int_{D} f(x) \phi_{k}(x) \psi_{l}(\eta) \widehat{\rho}(\eta) dx d\eta \quad (29)$$

for each  $k = 1, ..., n_x$  and  $l = 1, ..., n_\eta$ .

### Stochastic Galerkin method

 $\bullet\,$  Define  $\mu_0=1$  and  $\eta_0=1,$  so the KL expansion can be written

$$\widehat{k}(x,\eta) = \sum_{s=0}^{m} \sqrt{\mu_s} k_s(x) \eta_s .$$
(30)

• The solution u can be found by solving  $\widehat{A}u = b$  where

$$\widehat{A} = \sum_{p=0}^{m} G_p \otimes A_p \tag{31}$$

$$[A_p]_{ik} = \int_D \sqrt{\mu_p} k_p(x) \nabla \phi_i(x) \cdot \nabla \phi_k(x) dx \qquad (32)$$

$$[G_{p}]_{jl} = \int_{\Gamma} \eta_{p} \psi_{j}(\eta) \psi_{l}(\eta) \widehat{\rho}(\eta) d\eta$$
(33)

$$b = \int_{D} f(x)\phi_{k}(x)dx \int_{\Gamma} \psi_{l}(\eta)\widehat{\rho}(\eta)d\eta \qquad (34)$$

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#### Stochastic Galerkin method

• The mean and the variance of the solution are

$$E[u(x,\eta)] = \sum_{i=1}^{n_x} u_{i1}\phi_i(x)$$
 (35)

$$\operatorname{Var}[u(x,\eta)] = \sum_{i=1}^{n_x} \sum_{k=1}^{n_x} \sum_{j=2}^{n_\eta} u_{ij} u_{kj} \phi_i(x) \phi_k(x)$$
(36)

# Orthogonal polynomials

- Introduce the assumption  $\hat{\rho}(\eta) = \hat{\rho}_1(\eta_1)\hat{\rho}_2(\eta_2)...\hat{\rho}_m(\eta_m).$
- The integral for  $[G_p]_{jl}$  becomes

$$[G_{\rho}]_{jl} = \int_{\Gamma_{1}} \psi_{j}(\eta_{1})\psi_{j}(\eta_{1})\psi_{l}(\eta_{1})\widehat{\rho}_{1}(\eta_{1})d\eta_{1}...$$

$$\int_{\Gamma_{\rho}} \eta_{\rho}\psi_{j}(\eta_{\rho})\psi_{l}(\eta_{\rho})\widehat{\rho}_{\rho}(\eta_{\rho})d\eta_{\rho}...$$

$$\int_{\Gamma_{m}} \psi_{j}(\eta_{m})\psi_{l}(\eta_{m})\widehat{\rho}_{m}(\eta_{m})d\eta_{m}$$
(37)

• For each of the random variables the *i*th component of the orthogonal polynomials  $\psi_j(\eta_i)$  is constructed using the three-term recurrence relation, where the coefficients are found using the Stieljtes procedure.

# Orthogonal polynomials

• The k + 1 degree polynomial is:

$$\psi_{k+1}(\eta_i) = (\eta_i - \alpha_k)\psi_k(\eta_i) - \beta_k\psi_{k-1}(\eta_i)$$
(38)

for k = 0, 1, ..., where  $\psi_{-1}(\eta_i) = 0$  and  $\psi_0(\eta_i) = 1$ .

• The recurrence coefficients are

$$\alpha_{k} = \frac{\int \eta_{i} \psi_{k}(\eta_{i}) \psi_{k}(\eta_{i}) \rho_{i}(\eta_{i}) d\eta_{i}}{\int \psi_{k}(\eta_{i}) \psi_{k}(\eta_{i}) \rho_{i}(\eta_{i}) d\eta_{i}}$$
(39)

for  $k = 0, 1, 2, \dots$  and

$$\beta_{k} = \frac{\int \psi_{k}(\eta_{i})\psi_{k}(\eta_{i})\rho_{i}(\eta_{i})d\eta_{i}}{\int \psi_{k-1}(\eta_{i})\psi_{k-1}(\eta_{i})\rho_{i}(\eta_{i})d\eta_{i}}$$
(40)

for k = 1, 2, ....

- Let [a, b] be the support of  $\rho_i(\eta_i)$  and discretize with R points.
- The coefficients are:

$$\alpha_{k,R} = \frac{\sum_{t=1}^{R} \eta_{i_t} w_t \psi_{k,R}(\eta_{i_t}) \psi_{k,R}(\eta_{i_t}) \rho_i(\eta_{i_t})}{\sum_{t=1}^{R} w_t \psi_{k,R}(\eta_{i_t}) \psi_{k,R}(\eta_{i_t}) \rho(\eta_{i_t})}$$
(41)  
$$\beta_{k,R} = \frac{\sum_{t=1}^{R} w_t \psi_{k,R}(\eta_{i_t}) \psi_{k,R}(\eta_{i_t}) \rho_i(\eta_{i_t})}{\sum_{t=1}^{R} w_t \psi_{k-1,R}(\eta_{i_t}) \psi_{k-1,R}(\eta_{i_t}) \rho(\eta_{i_t})}$$
(42)

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• The weights and nodes are found using a Fejer quadrature where the nodes are related to the roots of the Chebyshev polynomials.

$$\eta_{\nu} = \frac{1}{2}(b-a)\cos\left(\frac{2\nu-1}{2M}\right) + \frac{1}{2}(a+b)$$
(43)  
$$w_{\nu} = \frac{1}{M}\left(1 - 2\sum_{n=1}^{\lfloor M/2 \rfloor} \frac{\cos(2n(\frac{2\nu-1}{2M}))}{4n^2 - 1}\right)$$
(44)

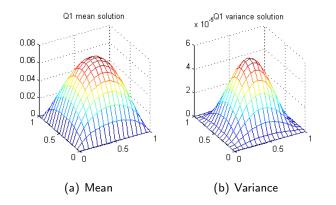
for v = 1, ..., M.

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# Stieljtes procedure

- The procedure was implemented for Matlab by Gautschi [4] where the interval is broken up into component intervals.
- This procedure was called to construct the polynomials for each of the *m* marginal density functions.

Figure: Stochastic Galerkin solution:  $E[k(x, \eta)] = 1$ , f(x) = 1, m = 1,  $\sigma = 0.1$ ,  $b_x = b_y = 10$ .



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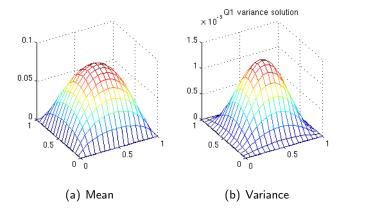
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- Validation of the stochastic Galerkin method is acheived by comparing with the Monte-Carlo solution.
- With standard deviation,  $\sigma = 0.1$ , and correlation lengths,  $b_x = b_y = 10$  the first eigenvalue includes 93.22% of the variance.

$$\frac{||E[u]_{MC} - E[u]_{SG}||_2}{||E[u]_{MC}||_2} = 4.61 \times 10^{-4}$$
$$\frac{||sd_{MC} - sd_{SG}||_2}{||sd_{MC}||_2} = 9.00 \times 10^{-3}$$

 Given the small standard deviation, the solution is not so different from the deterministic result.

Figure: Stochastic Galerkin solution:  $E[k(x, \eta)] = 1$ , f(x) = 1, m = 2,  $\sigma = 0.5$ ,  $b_x = b_y = 10$ .



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Introduction	Karhunen-Loéve expansion	Monte-Carlo method	Stochastic Galerkin method	Results
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Results	m = 2			

- Assume  $\widehat{\rho}(\eta) = \rho_1(\eta_1)\rho_2(\eta_2)$ .
- $\sigma = 0.5$  and  $b_x = b_y = 10$ , which incorporates 94.67% of the variance in the first two eigenvalues.

$$\frac{|E[u]_{MC} - E[u]_{SG}||_2}{||E[u]_{MC}||_2} = 3.95 \times 10^{-3}$$
$$\frac{||sd_{MC} - sd_{SG}||_2}{||sd_{MC}||_2} = 1.32 \times 10^{-1}$$

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- The Monte-Carlo method with q = 100,000 takes approximately 3.5 hours.
- The stochastic Galerkin method took approximately 0.5 hours.
- Unlike the Monte-Carlo method, the SG method scales as a function of the number of random variables.
- The majority of the time spent on the stochastic Galerkin method is in computing the two marginal density functions needed.

Denverables

- Code to compute the moments of the solution using the Monte-Carlo method
  - Verified using  $\sigma=$  0 and comparing with deterministic solution.
- Code to compute the moments of the solution using a KL expansion and stochastic Galerkin method.
  - Implemented for expansions of up to two random variables and standard deviation up to  $\sigma=0.5$  and verified using the Monte-Carlo results.
- Comparison of the results for varying number of terms in the KL expansion.
- Comparison of computational cost for the two methods

- The stochastic Galerkin method for performs faster than Monte-Carlo methods for m = 1 and m = 2.
- A different guadrature routine to compute the marginal density functions could improve computation time.
- The assumption about separability of the density function does not hold for standard deviations much higher than  $\sigma = 0.5$ .
- Having the joint density function illustrates using the direct expansion of the lognormal random field can be used to solve this problem.
- The stochastic collocation method does not require orthogonal polynomials, so no assumption of separability would be needed.

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