

(1) HW 4, Problem 2.

Consider the map F from the unit sphere $x^2 + y^2 + z^2 = 1$ to the ellipsoid $\frac{x^2}{4} + \frac{y^2}{9} + z^2 = 1$ given by $(x, y, z) \mapsto (2x, 3y, z)$.

- a) compute $dF_p(v)$ for $p = (\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$ and $v = (1, 2, -3)$.
 b) Compute the matrix of dF_p with respect to parametrizations ϕ of the sphere and ψ of the ellipsoid given by $\phi(u, v) = (u, v, \sqrt{1 - u^2 - v^2})$,
 $\psi(u, v) = (u, v, \sqrt{1 - \frac{u^2}{4} - \frac{v^2}{9}})$

Solution

- a) Let $\bar{F}: R^3 \rightarrow R^3$ be the map $(x, y, z) \mapsto (2x, 3y, z)$. Then F is just the restriction of \bar{F} to S . Therefore $dF_p(v) = d\bar{F}_p(v)$. Since \bar{F} is a linear map we easily compute that $d\bar{F} = \bar{F}$ i.e $d\bar{F}_p(v_1, v_2, v_3) = (2v_1, 3v_2, v_3)$. Hence $d\bar{F}_p(1, 2, -3) = (2, 6, -3)$
 b) The matrix of dF_p with respect to these parametrizations is equal to $d(\psi^{-1} \circ F \circ \phi)_{(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})}$. We compute $F(\phi(u, v)) = (2u, 3v, \sqrt{1 - u^2 - v^2})$ and hence $\psi^{-1}(F(\phi(u, v))) = (u, v)$. This map is linear. Hence it's equal to its differential and

$$dF_p = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$$

(2) HW7, Problem 4

Let $\kappa(\theta)$ be the principal curvature of the unit vector in T_pS making angle θ with the first principal direction.

Show that

$$H(p) = \frac{1}{2\pi} \int_0^{2\pi} \kappa(\theta) d\theta$$

Solution

Since the shape operator is symmetric, T_pS has an orthonormal basis of eigendirections. By an appropriate change of parametrization $\phi(u, v)$ we can assume that $\phi(0, 0) = p$, and the vectors $e_1 = \phi_u(0, 0)$ and $e_2 = \phi_v(0, 0)$ are eigendirections of S_p with corresponding principal curvatures k_1, k_2 . As usual let $A = -S_p$.

By above $A = \begin{pmatrix} k_1 & 0 \\ 0 & k_2 \end{pmatrix}$ with respect to e_1, e_2 .

Because e_1, e_2 are orthonormal the matrix of A is the same as the matrix of the second fundamental form

$$II = \begin{pmatrix} E & F \\ F & G \end{pmatrix} = \begin{pmatrix} (Ae_1, e_1) & (Ae_2, e_1) \\ (Ae_1, e_2) & (Ae_2, e_2) \end{pmatrix}$$

Therefore $II(v_1, v_2) = k_1 v_1^2 + k_2 v_2^2$ for any $v = (v_1, v_2)$. The unit vector v in T_pS making angle θ with e_1 is equal to $(\cos \theta, \sin \theta)$. Therefore, $\kappa(\theta) = II(v) = k_1 \cos^2 \theta + k_2 \sin^2 \theta$.

Finally, integrating the above expression for $\kappa(\theta)$ we obtain

$$\frac{1}{2\pi} \int_0^{2\pi} \kappa(\theta) d\theta = \frac{1}{2\pi} \int_0^{2\pi} (k_1 \cos^2 \theta + k_2 \sin^2 \theta) d\theta = \frac{k_1 + k_2}{2}$$

- (3) HW8, Problem 4
 (4) Let S be the surface of revolution $\phi(u, v) = (f(u) \cos v, f(u) \sin v, g(u))$ obtained by rotating the unit speed curve $(f(u), g(u))$ in the xz plane around the z axis.

Let $\gamma(t) = \phi(u(t), v(t))$ be a unit speed geodesic on S .

- (a) Write down the geodesic equations for $(u(t), v(t))$.
 (b) Use the geodesic equations to show that any meridian of S (i.e. any curve $v = \text{const}$) is a geodesic.
 (c) Show that a parallel $u = u_0 = \text{const}$ is a geodesic iff $f'(u_0) = 0$.
 (d) Find all surfaces of revolution for which *all* parallels are geodesics.

Solution

- (a) We first compute the first fundamental form of S which is easily seen to be equal to

$$I = \begin{pmatrix} 1 & 0 \\ 0 & f^2(u) \end{pmatrix}$$

The general geodesic equations for a curve $u(t), v(t)$ to be a geodesic are

$$\frac{d}{dt}(Eu' + Fv') = \frac{1}{2}(E_u(u')^2 + 2F_u u'v' + G_u(v')^2)$$

$$\frac{d}{dt}(Fu' + Gv') = \frac{1}{2}(E_v(u')^2 + 2F_v u'v' + G_v(v')^2)$$

In our case $E = 1, F = 0, G = f^2(u)$ and the above equations reduce to

$$u'' = f(u)f'(u)(v')^2 \quad \text{and} \quad \frac{d}{dt}(f^2(u)v') = 0$$

- (b) Let $u(t) = t, v(t) = v_0 = \text{const}$. Then the first equation becomes $0 = 0$ and the second $\frac{d}{dt}(f^2(u)0) = 0$. Both are obviously satisfied and hence $u(t), v(t)$ is a geodesic.
 (c) Let $u = u_0, v = v(t)$ be a unit speed geodesic. Since the curve is unit speed we have $1 = I(u', v') = f^2(u_0)(v'(t))^2$. In particular, $f(u_0) \neq 0$ and $v'(t) \neq 0$. The first geodesic equation gives $0 = f'(u_0)f(u_0)(v')^2$ which by above means that $f'(u_0) = 0$. Conversely, if $f'(u_0) = 0$, then it's immediate to check that the curve $u(t) = u_0, v(t) = t$ satisfies the geodesic equations.

- (d) By above, every parallel is a geodesic iff $f'(u) = 0$ for any u i.e $f = \text{const}$. This means that the only such surface of revolution is a cylinder.